takes place. In addition, the present invention performs the matching process between the edge images and the templates of the design data, and performs the matching process after re-registering the part of the SEM image corresponding to the detected position as the template. Therefore, a stable matching process with a high correlation value and a high detection ratio can be achieved.

Amend claim 1:

1. (Amended) A semiconductor inspection system, comprising:

a navigation system for storing semiconductor chip design information such as CAD data and for setting capturing and inspecting conditions including a region on a semiconductor wafer subject to inspection based on the design information; and

a scanning electron microscope system for performing an inspection by actually capturing the semiconductor wafer in accordance with the capturing and inspecting conditions set;

wherein the navigation system sets a template based on the design information, performs a matching process, by using the template, with respect to a pattern within an image provided by the scanning electron microscope system, and re-registers a portion of the image that corresponds to the template as a template.



Add new claims 24 and 25:

24. (New) A semiconductor inspection method by which a pattern within an image provided by a scanning electron microscope is determined by using a template that is registered in advance, the method comprising the steps of:

creating a template based on semiconductor chip design information such as CAD data;

detecting, by a pattern matching process, a position in an image provided by the scanning electron microscope which corresponds to the template; and

re-registering an image portion corresponding to the detected position as a template.

25. (New) A semiconductor inspection comprising:

a navigation system for registering a template used for a matching process for the identification of a portion of a semiconductor wafer subject to inspection; and

a scanning electron microscope system for forming an image based on the irradiation of the semiconductor wafer with an electron beam;

wherein the navigation system sets the template based on semiconductor chip design information such as CAD data, performs a matching process, by using the template, with respect to a pattern within an image provided by the scanning electron microscope system, and re-registers as a template a portion of the image that is detected by the matching process and which corresponds to the template.